

L Number	Hits	Search Text	DB	Time stamp
1	53424	vehicle and force and torque	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:49
2	79	(acceleration near6 sensor)and (longitudinal near6 acceleration)and (transverse near6 acceleration)and (vertical near6 acceleration)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:17
4	55	(spatial near6 angular near6 velocity)and (time near6 derivative)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:31
5	1	(vehicle and force and torque) and ((spatial near6 angular near6 velocity)and (time near6 derivative))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:31
6	68	(spatial same angular same velocity)and (time near6 derivative)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:19
7	2	(vehicle and force and torque) and ((spatial same angular same velocity)and (time near6 derivative))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:41
8	887	( angular same velocity)and (time near6 derivative)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:54
9	156	(vehicle and force and torque) and (( angular same velocity)and (time near6 derivative))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:19
10	97	rollover and roll\$6 and pitch\$5 and ((yaw near6 velocity)or (yaw near6 acceleration))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:21
11	68	(vehicle and force and torque) and (rollover and roll\$6 and pitch\$5 and ((yaw near6 velocity)or (yaw near6 acceleration)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:21
12	3258	yaw near6 rate near6 sensor	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:22
14	3922	(wheel near6 force)and sum	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:01
15	309	(wheel near6 force)and (wheel near6 force near6 sum)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:22
16	156	(vehicle and force and torque) and ((wheel near6 force)and (wheel near6 force near6 sum))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:22

17	57	vehicle and force and torque and (roll near6 angle near6 velocity)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:23
18	40	vehicle and force and torque and (roll near6 angle near6 velocity)and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:24
19	211	vehicle and force and torque and (tire near6 contact near6 force)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:36
21	5	vehicle and force and torque and ( tire near6 contact near6 force near5 sum)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:24
20	6	vehicle and force and torque and (sum near6 tire near6 contact near6 force)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:24
22	4	vehicle and force and torque and (tire near6 contact near6 force)and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:37
23	2	(tire near6 contact near6 force near6 sum)and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:37
24	6	(tire near6 contact near6 force )and sum and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:38
25	7	(tire near6 contact near6 force ) and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 15:38
3	11	((vehicle and force and torque) and ((acceleration near6 sensor)and (longitudinal near6 acceleration)and (transverse near6 acceleration)and (vertical near6 acceleration)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:21
28	11	((vehicle and force and torque) and (( angular same velocity)and (time near6 derivative))) and (rollover and roll\$6 and pitch\$5 and ((yaw near6 velocity)or (yaw near6 acceleration)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:31
30	11	(( angular same velocity)and (time near6 derivative)) and (rollover and roll\$6 and pitch\$5 and ((yaw near6 velocity)or (yaw near6 acceleration)))	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:41
13	61	((vehicle and force and torque) and (rollover and roll\$6 and pitch\$5 and ((yaw near6 velocity)or (yaw near6 acceleration)))) and (yaw near6 rate near6 sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:41
31	83	(vehicle and force and torque)and rollover and (yaw near6 velocity)and (yaw near6 acceleration)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:49

32	6	(vehicle and force and torque)and rollover and (yaw near6 velocity)and (yaw near6 acceleration)and (angular near6 velocity)and (time same derivative)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:52
33	2	(vehicle and force and torque)and rollover and (yaw adj velocity)and (yaw adj acceleration)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 16:52
34	23	( angular same velocity)and (time near6 derivative)and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:01
35	1730	(vehicle and force and torque) and ((wheel near6 force)and sum)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:01
36	97	(wheel near6 force)and sum and rollover	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:02
37	83	(wheel near6 force)and sum and rollover and vehicle and torque	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:02
38	83	(wheel near6 force)and sum and rollover and vehicle and torque and force	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:02
39	65	(wheel near6 force)and sum and rollover and vehicle and torque and force and (yaw near6 rate near6 sensor)	USPAT; US-PGPUB; EPO; JPO; DERWENT; IBM_TDB	2004/10/19 17:02